

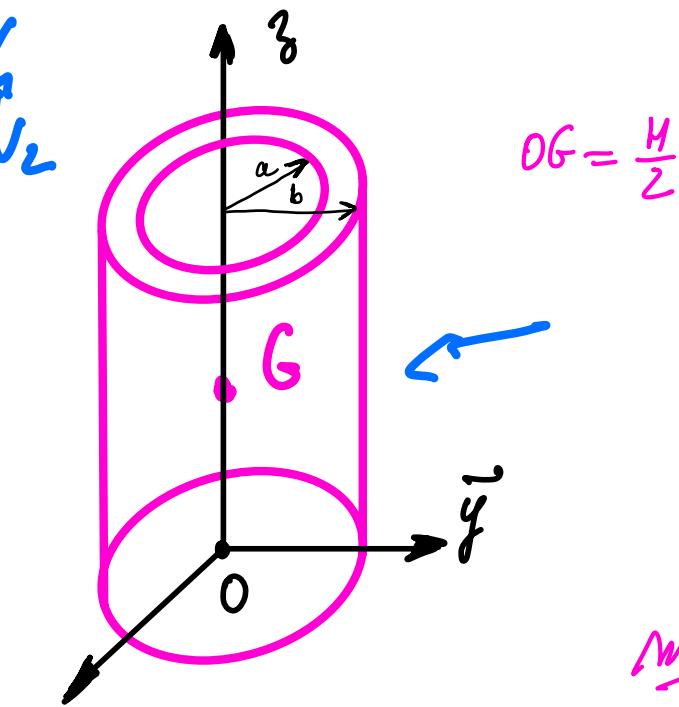
TUBE

$$m_1 = \rho \frac{\pi}{4} b^2 H$$

$$m_2 = \rho \frac{\pi}{4} a^2 H$$

$$J(O, \text{Tube}) = \begin{bmatrix} A_0 & A_0 \\ A_0 & C_0 \end{bmatrix}_R$$

Calcul de C_0



$$S_1: \text{Cylindre plein de rayon } b \quad \leftrightarrow \quad C_1 = \cancel{\frac{m_1 b^2}{2}}$$

$$S_2: \text{Cylindre plein de rayon } a \rightarrow C_2 = \cancel{\frac{m_2 a^2}{2}}$$

$$\text{Tube } S_1 - S_2 \rightarrow C_0 = C_1 - C_2 = \cancel{\frac{m_1 b^2}{2} - \cancel{\frac{m_2 a^2}{2}}}$$

$$C_0 = \frac{m_1 b^2}{2} - \frac{m_2 a^2}{2}$$

$$\eta = \frac{m}{\pi(b^2-a^2)H} = \frac{m_1}{\pi b^2 H} = \frac{m_2}{\pi a^2 H}$$

$$m_1 = \frac{b^2}{b^2-a^2} m \quad \text{et} \quad m_2 = \frac{a^2}{b^2-a^2} m$$

$$C_0 = \frac{m b^4}{2(b^2-a^2)} - \frac{m a^4}{2(b^2-a^2)} = \frac{m}{2} \frac{b^4-a^4}{b^2-a^2} = \frac{m}{2} (b^2+a^2)$$

$$C_0 = \gamma \left[\frac{\omega^2}{\frac{R}{2}} \right]^R \left[\theta \right] \left[3 \right]_0^H = \gamma \frac{R^4}{4} 2\pi H$$

et $\gamma = \frac{m}{V} = \frac{m}{\pi R^2 H} \Rightarrow C_0 = \frac{m}{\cancel{\pi R^2 H}} \frac{\cancel{R^4}}{4} \cancel{2\pi H}$

$$C_0 = m \frac{R^2}{2}$$

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$$C_0 = \gamma \left[\frac{a^4}{b} \right]^b \left[\theta \right]_0^{2\pi} \left[3 \right]_0^H$$

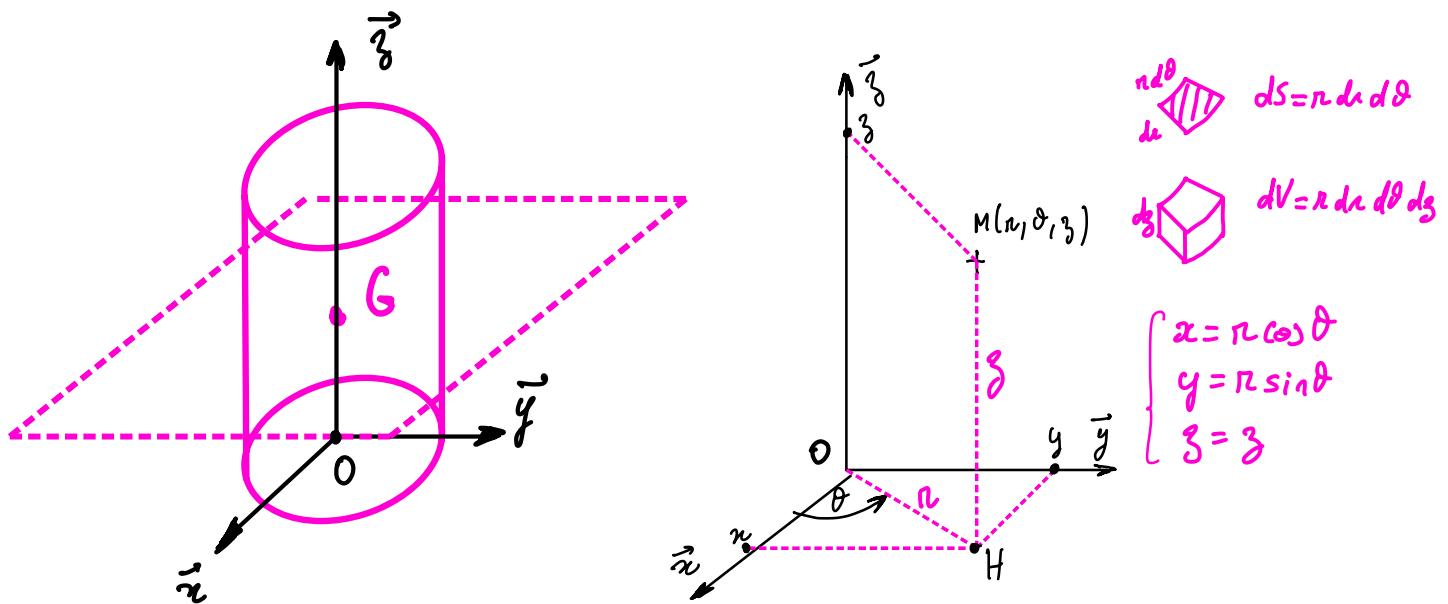
$$C_0 = \gamma \frac{b^4 - a^4}{4} 2\pi H = \frac{m}{V} \frac{b^4 - a^4}{4} 2\pi H$$

$$C_0 = \frac{m}{\cancel{\pi(b^2 - a^2)H}} \frac{b^4 - a^4}{4} \cancel{2\pi H}$$

$$C_0 = \frac{m}{2} \frac{b^4 - a^4}{b^2 - a^2} = \frac{m}{2} \frac{(b^2 - a^2)(b^2 + a^2)}{\cancel{(b^2 - a^2)}}$$

$$C_0 = \frac{m}{2} (b^2 + a^2)$$

Opérateur d'inertie du cylindre d'axe z , de rayon R et de hauteur H



$$PS \quad x_{CG} \rightarrow y_{CG} = 0 \quad PS \quad y_{CG} \Rightarrow x_{CG} = 0 \quad SG = \frac{H}{2}$$

$$J(O, S) = \begin{bmatrix} A_0 & 0 & 0 \\ 0 & A_0 & 0 \\ 0 & 0 & C_0 \end{bmatrix}_R \quad \begin{array}{l} EPS \Rightarrow D=E=F=0 \\ A=B \end{array}$$

$$C_0 = I(S/\theta_3) = \iiint (x^2 + y^2) dm = \iiint r^2 dm = \iiint r^2 y dv$$

$$C_0 = \eta \iiint r^2 y dr d\theta dz = \eta \int_0^R r^2 dr \int_0^{2\pi} d\theta \int_0^H dz$$

$$C_0 = \eta \left[\frac{r^4}{4} \right]_0^R \left[\theta \right]_0^{2\pi} \left[z \right]_0^H = \eta \frac{R^4}{4} 2\pi H$$

$$\text{et } \eta = \frac{m}{V} = \frac{m}{\pi R^2 H} \Rightarrow C_0 = \frac{m}{\cancel{\pi R^2 H}} \frac{R^2}{\cancel{4}} \cancel{2\pi H}$$

$C_0 = m \frac{R^2}{2}$

en kg m^2