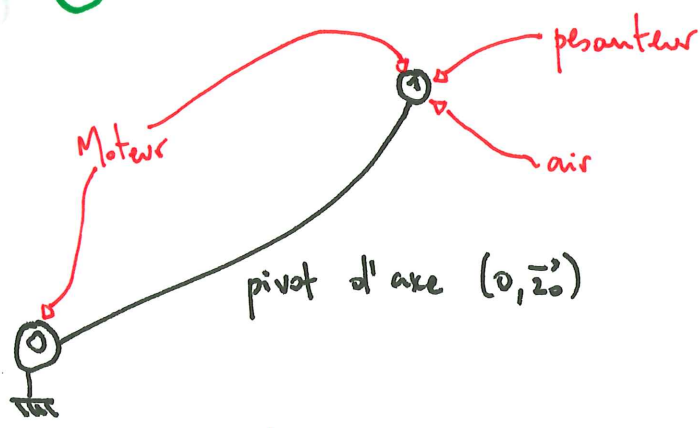


Hélice de ventilateur

①



$$\left\{ \begin{array}{l} \vec{0} \xrightarrow{P} 1 \\ \vec{0} \xrightarrow{\text{pivot}} 1 \end{array} \right. = \int \vec{R}_{0 \rightarrow 1} = x_{01} \cdot \vec{n}_3 + y_{01} \cdot \vec{y}_0 + z_{01} \cdot \vec{z}_0$$

$$\vec{0} \xrightarrow{\vec{P}_{0,0}} 1 = L_{01} \cdot \vec{n}_3 + \eta_{01} \cdot \vec{y}_0 \pm C_r \cdot \vec{z}_0 - f \cdot \dot{\theta} \cdot \vec{z}_0 = -f \cdot \vec{J}_{G,1/0}$$

f : coefficient de frottement visqueux (N.m/(rad/s))
 C_r : " " " " sec (N.m)

② J'isole 1 soumis aux actions mécaniques extérieures suivantes:

- $\vec{0} \xrightarrow{P} 1$
- $\vec{0} \xrightarrow{\text{mot}} 1$
- $\text{air} \rightarrow 1$
- $P_3 \rightarrow 1$

J'écris le th. des moments en G et en projection sur \vec{z}_0 :

$$\underbrace{\vec{M}_{G,0 \rightarrow 1} \cdot \vec{z}_0}_{\pm C_r - f \cdot \dot{\theta}} + \underbrace{\vec{M}_{G,0 \xrightarrow{\text{mot}} 1} \cdot \vec{z}_0}_{C_m} + \underbrace{\vec{M}_{G,P_3 \rightarrow 1} \cdot \vec{z}_0}_0 + \underbrace{\vec{M}_{G,\text{air} \rightarrow 1} \cdot \vec{z}_0}_{-f_{\text{air}} \cdot \dot{\theta}} = \vec{S}_{G,1/0} \cdot \vec{z}_0$$

$$\vec{S}_{G,1/0} \cdot \vec{z}_0 = \frac{d}{dt} (\vec{r}_{G,1/0})_0 \cdot \vec{z}_0 + (m \cdot \underbrace{\vec{J}_{G/0} \wedge \vec{J}_{G \in 1/0}}_{\Rightarrow \vec{0} \text{ car } \hat{n} \text{ vitene}}) \cdot \vec{z}_0$$

$$= \frac{d}{dt} (\vec{r}_{G,1/0} \cdot \vec{z}_0)$$

$$\text{Et } \vec{r}_{G,1/0} \cdot \vec{z}_0 = (I(G,1) \cdot \vec{J}_{1/0}) \cdot \vec{z}_0 + (m \cdot \vec{G} \wedge \vec{J}_{G \in 1/0}) \cdot \vec{z}_0$$

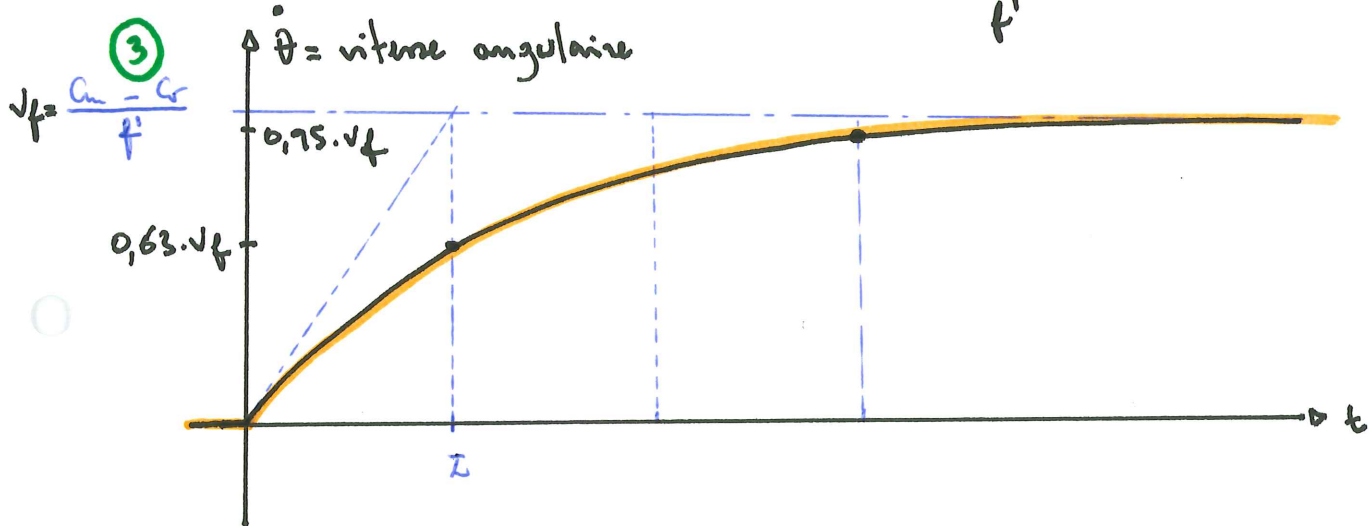
$$= \begin{bmatrix} A & -F & -E \\ \vdots & B & -D \\ \vdots & \vdots & \vdots \\ C & \vdots & \vdots \end{bmatrix}_1 \cdot \begin{bmatrix} \dot{\theta} \\ 0 \\ 0 \\ \vdots \\ \dot{\theta} \end{bmatrix}_1 \cdot \vec{z}_0$$

$$\vec{F}_{G,1b} \cdot \vec{z}_0 = (-E \cdot \dot{\theta} \cdot \vec{x}_1 - D \cdot \dot{\theta} \cdot \vec{y}_1 + C \cdot \dot{\theta} \cdot \vec{z}_1) \cdot \vec{z}_0$$

$$= C \cdot \dot{\theta}$$

donc $\vec{F}_{G,1b} \cdot \vec{z}_0 = C \cdot \dot{\theta}$

On a donc: $\underline{C_m \pm C_r = C \cdot \ddot{\theta} + \underbrace{(f + f_{air})}_{f'} \cdot \dot{\theta}}$



$$\frac{C_m \pm C_r}{C} = \ddot{\theta} + \frac{f'}{C} \cdot \dot{\theta}$$

$\ddot{\theta}$ (rad/s²)
 $\frac{f'}{C} \cdot \dot{\theta}$ (rad/s)
 $\Delta = \frac{1}{\tau}$