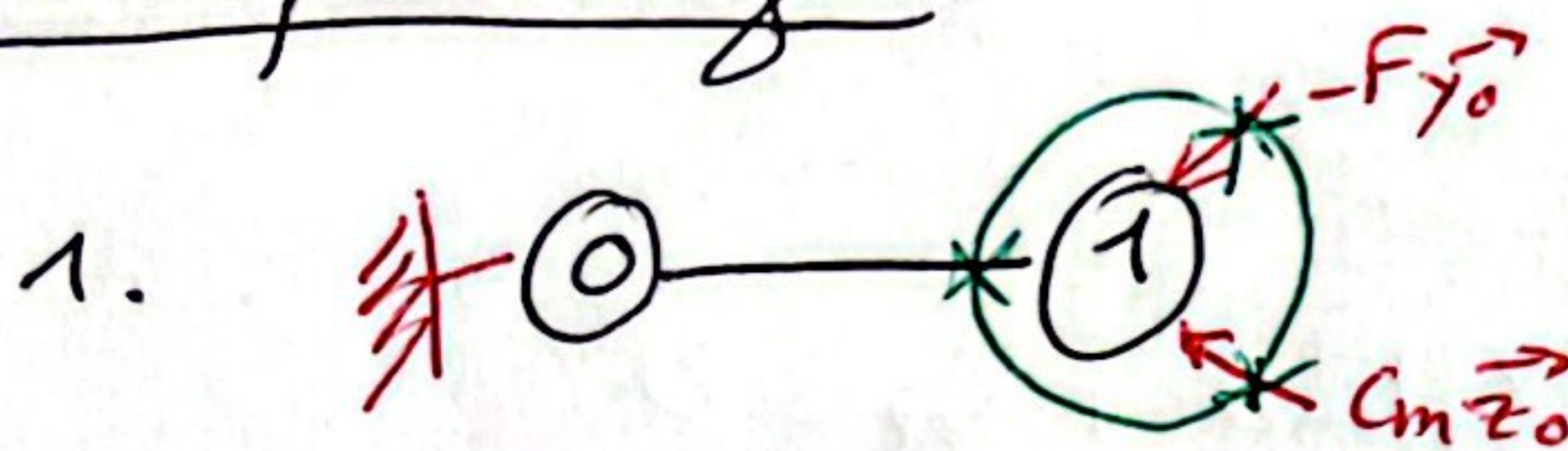


Exercices de statique corrigés

Levier



2. $\{T_{0 \rightarrow 1}\} = \begin{Bmatrix} X_{01} \\ Y_{01} \\ - \\ 0 \end{Bmatrix}_A$ pb. plan de $\perp \vec{z}_0$

3. $\{T_{0 \rightarrow 1}\} + \{T_{\vec{F} \rightarrow 1}\} + \{T_{\vec{C}_m \rightarrow 1}\} = \{0\}$

$$\begin{cases} X_{01} & + 0 & + 0 = 0 \\ Y_{01} & - F & + 0 = 0 \\ 0 & -FR \cos \theta & + C_m = 0 \end{cases}$$

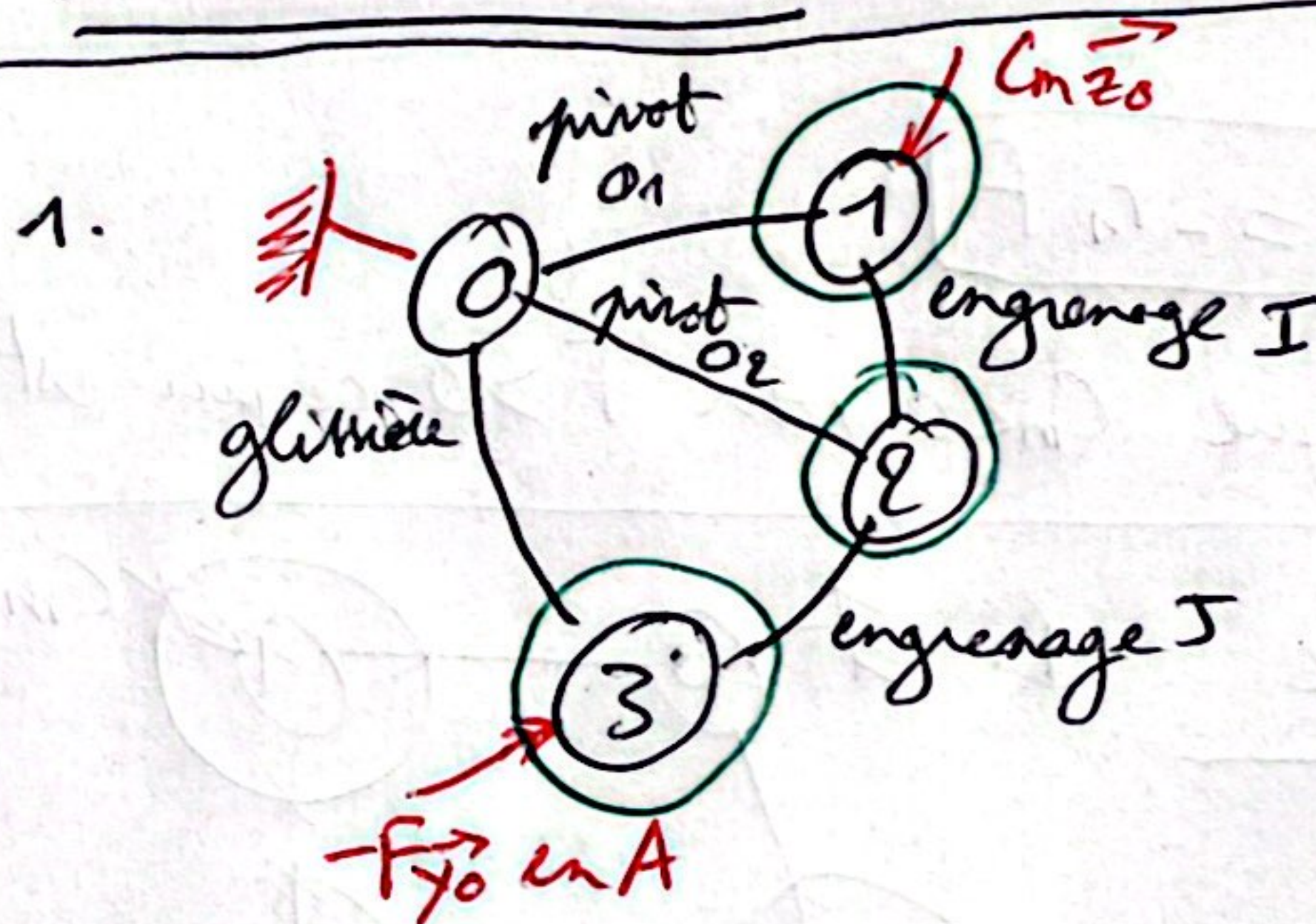
$0 - FR \cos \theta + C_m = 0 \leftarrow \text{eq utile}$

$$\vec{M}(A, \vec{F} \rightarrow 1) = \vec{AB} \wedge \vec{F} + \vec{M}(B, \vec{F} \rightarrow 1) = R \vec{x}_1 \wedge -F \vec{y}_0$$

$$\vec{x}_1 \wedge \vec{y}_0 = -\cos \theta \vec{z}_0$$

$$\boxed{C_m = F \cdot R \cos \theta}$$

Engrenage



2. $\{T_{0 \rightarrow 1}\} = \begin{Bmatrix} X_{01} \\ Y_{01} \\ - \\ 0 \end{Bmatrix}_{0_1}$; $\{T_{0 \rightarrow 2}\} = \begin{Bmatrix} X_{02} \\ Y_{02} \\ - \\ 0 \end{Bmatrix}_{0_2}$; $\{T_{0 \rightarrow 3}\} = \begin{Bmatrix} X_{03} \\ - \\ 0 \\ -N_{03} \end{Bmatrix}_p$ VP

$\{T_{1 \rightarrow 2}\} = \begin{Bmatrix} -Y_{12} \tan \alpha \\ Y_{12} \\ - \\ 0 \end{Bmatrix}_I$; $\{T_{2 \rightarrow 3}\} = \begin{Bmatrix} Y_{23} \tan \alpha \\ Y_{23} \\ - \\ 0 \end{Bmatrix}_J$

3. P.F.S. à 1 en 0_1 :

$$\begin{cases} X_{01} + Y_{12} \tan \alpha & + 0 = 0 & (1) \\ Y_{01} - Y_{12} & + 0 = 0 & (2) \\ 0 - Y_{12} \cdot r_1 & + C_m = 0 & (3) \end{cases}$$

$$\vec{M}(0_1, 2 \rightarrow 1) = \vec{M}(I \rightarrow 1) + \vec{O}_1 \vec{I} \wedge \vec{R}_{2 \rightarrow 1} = r_1 \vec{x}_0 \wedge (Y_{12} \tan \alpha \vec{x}_0 - Y_{12} \vec{y}_0)$$

PFS a 2 en O_2 :

$$\begin{cases} -Y_{12} \tan \alpha - Y_{23} \tan \alpha + X_{02} = 0 & (4) \\ Y_{12} - Y_{23} + \cancel{X_{02}} = 0 & (5) \\ -r_2 Y_{12} - r_2 Y_{23} + 0 = 0 & (6) \Rightarrow Y_{12} = -Y_{23} \end{cases}$$

$$\vec{M}(O_2, 1 \rightarrow 2) = \vec{O_2 I} \wedge \vec{R}_{1 \rightarrow 2} = -r_2 \vec{x}_0 \wedge (-y_{12} \tan \alpha \vec{x}_0 + y_{12} \vec{y}_0)$$

$$\vec{M}(0, 1, 3 \rightarrow 2) = \vec{O_2 J} \wedge \vec{R}_{3 \rightarrow 2} = + r_2 \vec{x}_0 \wedge (-\gamma_{23} \tan \alpha \vec{x}_0 - \gamma_{23} \vec{y}_0)$$

(car $\gamma_{23} = -\gamma_{32}$)

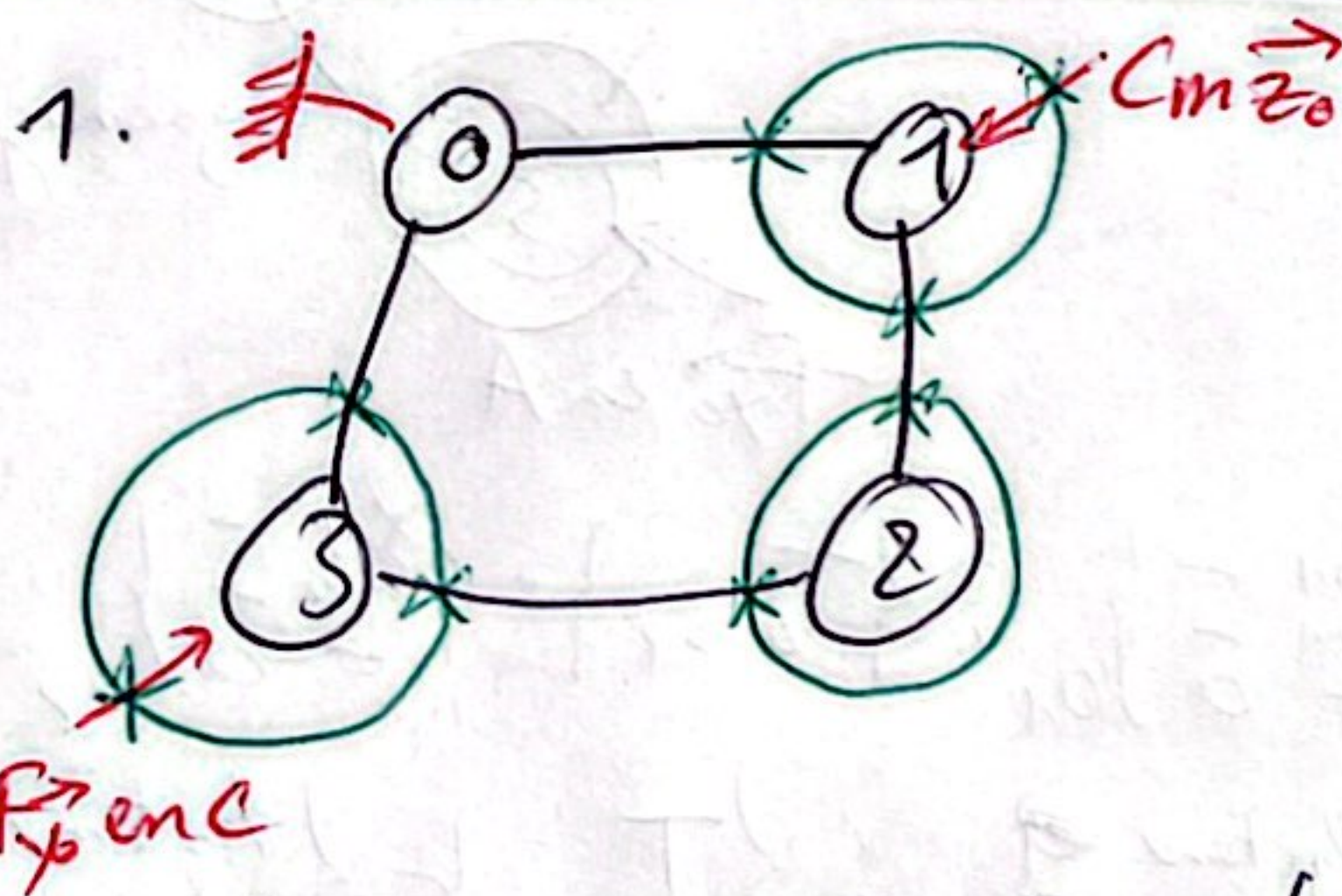
PFS $\bar{a}$ en $\mathbb{J}$:

$$\begin{cases} 0 + X_{03} + X_{23} \tan \alpha = 0 & (7) \\ -F + 0 + Y_{23} = 0 & (8) \\ 0 + N_{03} + 0 = 0 & (9) \end{cases}$$

③, ⑥ & ⑧ $\Rightarrow C_m = -r_1 F$

on remarque $C_m < 0$ pour $F > 0$ ce qui est cohérent.

Bille-Mamivelle



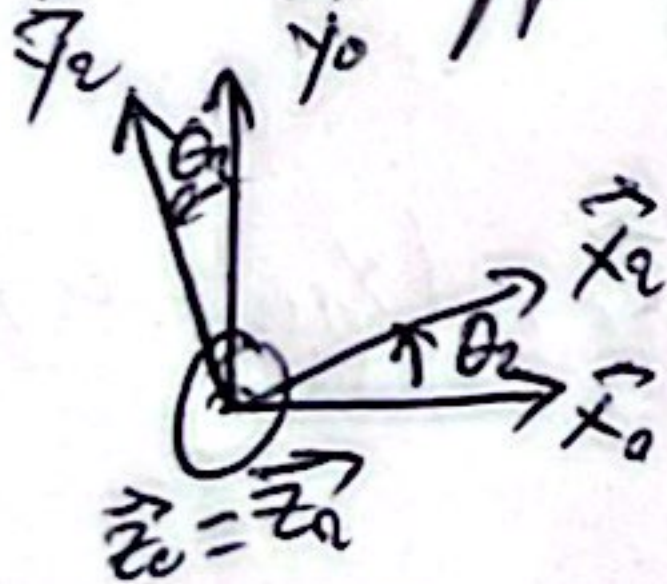
$$2. \quad \{T_{1 \rightarrow 2}\} = \left\{ \begin{array}{c} X_{12} \\ Y_{12} \\ - \\ 0 \end{array} \right\}_B; \quad \{T_{0 \rightarrow 1}\} = \left\{ \begin{array}{c} X_{01} \\ Y_{01} \\ - \\ 0 \end{array} \right\}_A; \quad \{T_{2 \rightarrow 3}\} = \left\{ \begin{array}{c} X_{23} \\ Y_{23} \\ - \\ 0 \end{array} \right\}_C$$

$$\{T_{0 \rightarrow 3}\} = \left\{ \begin{array}{c} X_{03} \\ 0 \\ - \\ 0 \end{array} \right\}_{Ap}$$

3. PFS $\xrightarrow{I_0}$ appliqué à 2 en B:

$$\{T_{1 \rightarrow 2}\} + \{T_{3 \rightarrow 2}\} = \{0\}$$

$$\begin{cases} X_{12} - X_{23} = 0 & (1) \\ Y_{12} - Y_{23} = 0 & (2) \\ 0 - L(\cos\theta_2 X_{23} + \sin\theta_2 Y_{23}) = 0 & (3) \end{cases}$$



can $\vec{M}(B, 3 \rightarrow 4) = \vec{M}(C, 3 \rightarrow 4) + \vec{BC} \wedge \vec{R}_{3 \rightarrow 4} = -L \vec{y}_2 \wedge (-x_{23} \vec{x}_0 - y_{23} \vec{y}_0)$

on en déduit ③ $\Rightarrow \boxed{X_{23} = -Y_{23} \tan \theta_2}$ et ④ $X_{12} = X_{23}$

4. P.F.S. appliquée à 3 en C :

$$\{T_{0 \rightarrow 3}\} + \{T_{2 \rightarrow 3}\} + \{T_e \rightarrow 3\} = \{0\}$$

$$\begin{cases} X_{03} & -\tan \theta_2 \cdot Y_{23} & + 0 & = 0 & \text{⑥} \\ \dot{O} & + Y_{23} & + F & = 0 & \text{⑤} \\ N_{03} & + 0 & + 0 & = 0 & \text{⑥} \end{cases} \Rightarrow \boxed{Y_{23} = -F}$$

j'utilise le résultat de ③

PFS appliquée à 1 en A :

$$\{T_{0 \rightarrow 1}\} + \{T_{2 \rightarrow 1}\} + \{T_e \rightarrow 1\} = \{0\}$$

$$\begin{cases} X_{01} & -\tan \theta_2 F & + 0 & = 0 & \text{⑦} \\ Y_{01} & + F & + 0 & = 0 & \text{⑧} \\ 0 & + eF(\cos \theta_1 + \sin \theta_1 \tan \theta_2) & + C_m & = 0 & \text{⑨} \end{cases}$$

$$\begin{aligned} \vec{M}(A, 2 \rightarrow 1) &= \vec{M}(B, 2 \rightarrow 1) + \vec{AB} \wedge \vec{R}_{2 \rightarrow 1} & \text{or } \vec{R}_{2 \rightarrow 1} &= (-\tan \theta_2 F \vec{x}_0 + F \vec{y}_0) \\ &= \vec{0} & + e \vec{x}_1 \wedge (-\tan \theta_2 F \vec{x}_0 + F \vec{y}_0) & \text{①, ③ et ⑤} \end{aligned}$$

$$\text{⑨} \Rightarrow \boxed{C_m = eF(\cos \theta_1 + \sin \theta_1 \tan \theta_2)}$$

remarque : * $\theta_1 = 0 \Rightarrow C_m = eF$

* $\theta_1 = \frac{\pi}{2} \Rightarrow \theta_2 = 0 \Rightarrow C_m = 0$