

Formulaire d'analyse vectorielle

Soit $f(x, y, z, t)$ un champ scalaire, $\vec{A}(x, y, z, t) = A_x(x, y, z, t)\vec{u}_x + A_y(x, y, z, t)\vec{u}_y + A_z(x, y, z, t)\vec{u}_z$ et $\vec{B}(x, y, z, t) = B_x(x, y, z, t)\vec{u}_x + B_y(x, y, z, t)\vec{u}_y + B_z(x, y, z, t)\vec{u}_z$ deux champs vectoriels.

I - Les opérateurs dans les différents systèmes de coordonnées

1) Coordonnées cartésiennes

• Opérateur nabla :
$$\vec{\nabla} = \frac{\partial}{\partial x}\vec{u}_x + \frac{\partial}{\partial y}\vec{u}_y + \frac{\partial}{\partial z}\vec{u}_z.$$

• Opérateur gradient :
$$\overrightarrow{\text{grad}}f = \vec{\nabla}f = \frac{\partial f}{\partial x}\vec{u}_x + \frac{\partial f}{\partial y}\vec{u}_y + \frac{\partial f}{\partial z}\vec{u}_z.$$

scalaire \rightarrow vecteur

On a $\overrightarrow{\text{grad}}f \cdot d\vec{\ell} = df$

• Opérateur divergence :
$$\text{div } \vec{A} = \vec{\nabla} \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}.$$

vecteur \rightarrow scalaire

• Opérateur rotationnel :
$$\overrightarrow{\text{rot}} \vec{A} = \vec{\nabla} \wedge \vec{A} = \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) \vec{u}_x + \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) \vec{u}_y + \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \vec{u}_z$$

vecteur \rightarrow vecteur

• Opérateur laplacien scalaire:
$$\Delta f = \vec{\nabla} \cdot \vec{\nabla} f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

scalaire \rightarrow scalaire

• Opérateur laplacien vectoriel :
$$\Delta \vec{A} = \Delta A_x \vec{u}_x + \Delta A_y \vec{u}_y + \Delta A_z \vec{u}_z.$$

vecteur \rightarrow vecteur

• "A scalaire gradient" appliqué à un scalaire :
$$\left(\vec{A} \cdot \overrightarrow{\text{grad}} \right) f = \vec{A} \cdot \left(\overrightarrow{\text{grad}} f \right) = A_x \frac{\partial f}{\partial x} + A_y \frac{\partial f}{\partial y} + A_z \frac{\partial f}{\partial z}$$

Appliqué à un vecteur :
$$\left(\vec{A} \cdot \overrightarrow{\text{grad}} \right) \vec{B} = \left(A_x \frac{\partial}{\partial x} + A_y \frac{\partial}{\partial y} + A_z \frac{\partial}{\partial z} \right) \vec{B} = \left(A_x \frac{\partial B_x}{\partial x} + A_y \frac{\partial B_x}{\partial y} + A_z \frac{\partial B_x}{\partial z} \right) \vec{u}_x + \left(A_x \frac{\partial B_y}{\partial x} + A_y \frac{\partial B_y}{\partial y} + A_z \frac{\partial B_y}{\partial z} \right) \vec{u}_y + \left(A_x \frac{\partial B_z}{\partial x} + A_y \frac{\partial B_z}{\partial y} + A_z \frac{\partial B_z}{\partial z} \right) \vec{u}_z$$

2) Coordonnées cylindriques

$$\overrightarrow{\text{grad}}f = \frac{\partial f}{\partial r}\vec{u}_r + \frac{1}{r} \frac{\partial f}{\partial \theta}\vec{u}_\theta + \frac{\partial f}{\partial z}\vec{u}_z.$$

$$\text{div } \vec{A} = \frac{1}{r} \frac{\partial(rA_r)}{\partial r} + \frac{1}{r} \frac{\partial A_\theta}{\partial \theta} + \frac{\partial A_z}{\partial z}. \text{ (pas à savoir)}$$

$$\overrightarrow{\text{rot}} \vec{A} = \left(\frac{1}{r} \frac{\partial A_z}{\partial \theta} - \frac{\partial A_\theta}{\partial z} \right) \vec{u}_r + \left(\frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right) \vec{u}_\theta + \frac{1}{r} \left(\frac{\partial(rA_\theta)}{\partial r} - \frac{\partial A_r}{\partial \theta} \right) \vec{u}_z. \text{ (pas à savoir)}$$

$$\Delta f = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2} + \frac{\partial^2 f}{\partial z^2}. \text{ (pas à savoir)}$$

3) Coordonnées sphériques

$$\overrightarrow{\text{grad}} f = \frac{\partial f}{\partial r} \vec{u}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \vec{u}_\theta + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \varphi} \vec{u}_\varphi.$$

$$\text{div } \vec{A} = \frac{1}{r^2} \frac{\partial(r^2 A_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\sin \theta A_\theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial A_\varphi}{\partial \varphi}. \quad (\text{pas à savoir})$$

$$\overrightarrow{\text{rot}} \vec{A} = \frac{1}{r \sin \theta} \left(\frac{\partial(\sin \theta A_\varphi)}{\partial \theta} - \frac{\partial A_\theta}{\partial \varphi} \right) \vec{u}_r + \left(\frac{1}{r \sin \theta} \frac{\partial A_r}{\partial \varphi} - \frac{1}{r} \frac{\partial(r A_\varphi)}{\partial r} \right) \vec{u}_\theta + \frac{1}{r} \left(\frac{\partial(r A_\theta)}{\partial r} - \frac{\partial A_r}{\partial \theta} \right) \vec{u}_\varphi. \quad (\text{pas à savoir})$$

$$\Delta f = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial f}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial^2 f}{\partial \varphi^2}. \quad (\text{pas à savoir})$$

II - Composition d'opérateurs

$$\begin{array}{ll} \overrightarrow{\text{rot}}(\overrightarrow{\text{grad}} f) = \vec{0} & (\vec{\nabla} \wedge (\vec{\nabla} f) = \vec{0}) \\ \text{div}(\overrightarrow{\text{rot}} \vec{A}) = 0 & (\vec{\nabla} \cdot (\vec{\nabla} \wedge \vec{A}) = 0) \\ \text{div}(\overrightarrow{\text{grad}} f) = \Delta f & (\vec{\nabla} \cdot (\vec{\nabla} f) = \Delta f) \\ \overrightarrow{\text{rot}}(\overrightarrow{\text{rot}} \vec{A}) = \overrightarrow{\text{grad}}(\text{div } \vec{A}) - \Delta \vec{A} & (\vec{\nabla} \wedge (\vec{\nabla} \wedge \vec{A}) = \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \Delta \vec{A}) \end{array}$$

III - Opérateurs et produits

$$\begin{array}{l} \overrightarrow{\text{grad}}(fg) = f \overrightarrow{\text{grad}} g + g \overrightarrow{\text{grad}} f \\ \text{div}(f \vec{A}) = f \text{div } \vec{A} + \overrightarrow{\text{grad}} f \cdot \vec{A} \\ \overrightarrow{\text{rot}}(f \vec{A}) = f \overrightarrow{\text{rot}} \vec{A} + \overrightarrow{\text{grad}} f \wedge \vec{A} \\ \text{div}(\vec{A} \wedge \vec{B}) = \vec{B} \cdot \overrightarrow{\text{rot}} \vec{A} - \vec{A} \cdot \overrightarrow{\text{rot}} \vec{B} \\ (\vec{A} \cdot \overrightarrow{\text{grad}}) \vec{A} = \frac{1}{2} \overrightarrow{\text{grad}} \|\vec{A}\|^2 + (\overrightarrow{\text{rot}} \vec{A}) \wedge \vec{A} \end{array}$$