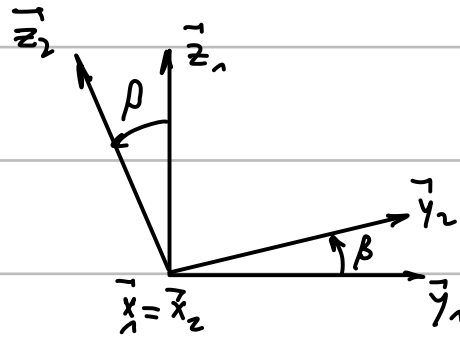
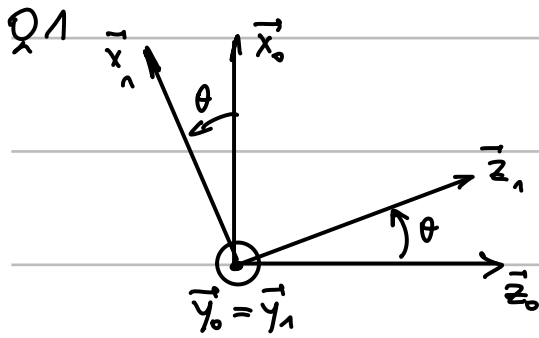


Exercice 1

Q2 : $\vec{\Omega}_{2/1} = \dot{\beta} \vec{x}_{12}$ $\vec{\Omega}_{1/0} = \dot{\theta} \vec{y}_{01}$ $\vec{\Omega}_{2/0} = \vec{\Omega}_{2/1} + \vec{\Omega}_{1/0}$
 $= \dot{\beta} \vec{x}_{12} + \dot{\theta} \vec{y}_{01}$

Exercice 2 :

Q1 : $\vec{\Omega}_{2/1} = \omega_{2/1} \vec{z}_{12}$

Q2 : On raisonne par rapport au solide 1

On a une transmission poulies/chaîne, donc :

$$\frac{\omega_{2/1}}{\omega_{0/1}} = \frac{R_0}{R_1} \quad \text{or} \quad \omega_{0/1} = -\omega_{1/0}$$

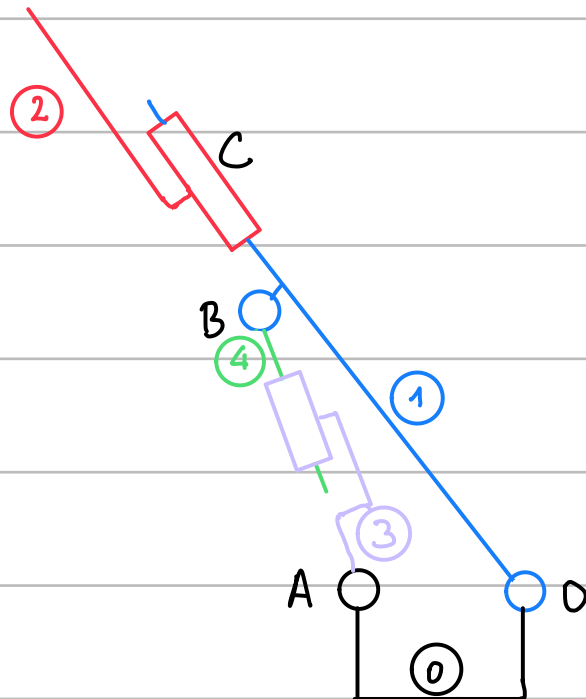
$$\text{d'où} \quad \frac{\omega_{2/1}}{\omega_{1/0}} = -\frac{R_0}{R_1}$$

$$\omega_{1/0} = -\frac{R_1}{R_0} \omega_{2/1}$$

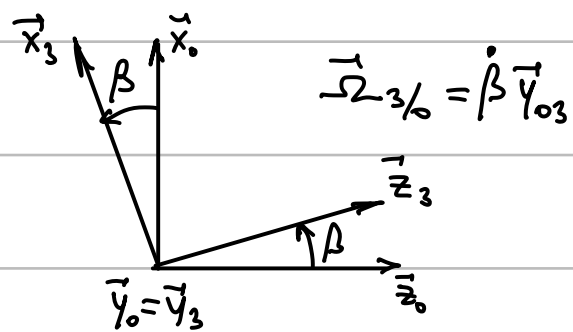
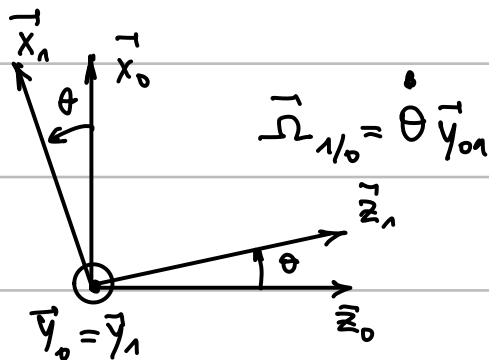
Q3 : $\vec{\Omega}_{1/0} = -\frac{R_1}{R_0} \omega_{2/1} \vec{z}_{01}$

Exercice 3:

Q1:



Q2



Q3: On écrit une fermeture géométrique entre O, A et B

$$\vec{F} = \vec{OA} + \vec{AB} + \vec{BO} = \vec{0}$$

$$\vec{F} = a\vec{x}_0 + \mu\vec{x}_3 - b\vec{x}_1 + c\vec{z}_1 = \vec{0}$$

$$\vec{F} = a\vec{x}_0 + \mu(-\sin\beta\vec{z}_0 + \cos\beta\vec{x}_0) - b(-\sin\theta\vec{z}_0 + \cos\theta\vec{x}_0) + c(\cos\theta\vec{z}_0 + \sin\theta\vec{x}_0) = \vec{0}$$

$$\vec{F} \cdot \vec{x}_0 = 0 = a + \mu \cos\beta - b \cos\theta + c \sin\theta \quad (1)$$

$$\vec{F} \cdot \vec{z}_0 = 0 = -\mu \sin\beta + b \sin\theta + c \cos\theta \quad (2)$$

$$(1) \text{ donne : } \mu \cos \beta = b \cos \theta - c \sin \theta - a$$

$$\mu \sin \beta = b \sin \theta + c \cos \theta$$

$$\text{d'où } \mu = \sqrt{(b \cos \theta - c \sin \theta - a)^2 + (b \sin \theta + c \cos \theta)^2}$$

$$= \sqrt{b^2 - 2b \cos \theta (c \sin \theta + a) + (c \sin \theta + a)^2 + c^2 \cos^2 \theta + 2bc \sin \theta \cos \theta}$$

$$= \sqrt{b^2 - 2bc \cancel{\cos \theta \sin \theta} - 2ba \cos \theta + c^2 \sin^2 \theta + 2ac \sin \theta + a^2 + c^2 \cos^2 \theta + 2bc \cancel{\sin \theta \cos \theta}}$$

$$\mu = \sqrt{b^2 + a^2 + c^2 + 2a(c \sin \theta - b \cos \theta)}$$

$$Q4 : \vec{V}_{ce2/1} = \frac{d}{dt} \vec{OC} \Big|_1 = \frac{d}{dt} \vec{x}_1 = \dot{\vec{x}}_1$$

$$Q5 : \vec{V}_{ce1/0} = \vec{V}_{oe1/0} + \vec{CO} \wedge \vec{\Omega}_{1/0} = -\dot{\theta} \vec{x}_1 \wedge \vec{y}_1 = -\dot{\theta} \vec{z}_1$$

$$Q6 : \vec{V}_{ce2/0} = \vec{V}_{ce2/1} + \vec{V}_{ce1/0} = \dot{\vec{x}}_1 - \dot{\theta} \vec{z}_1$$

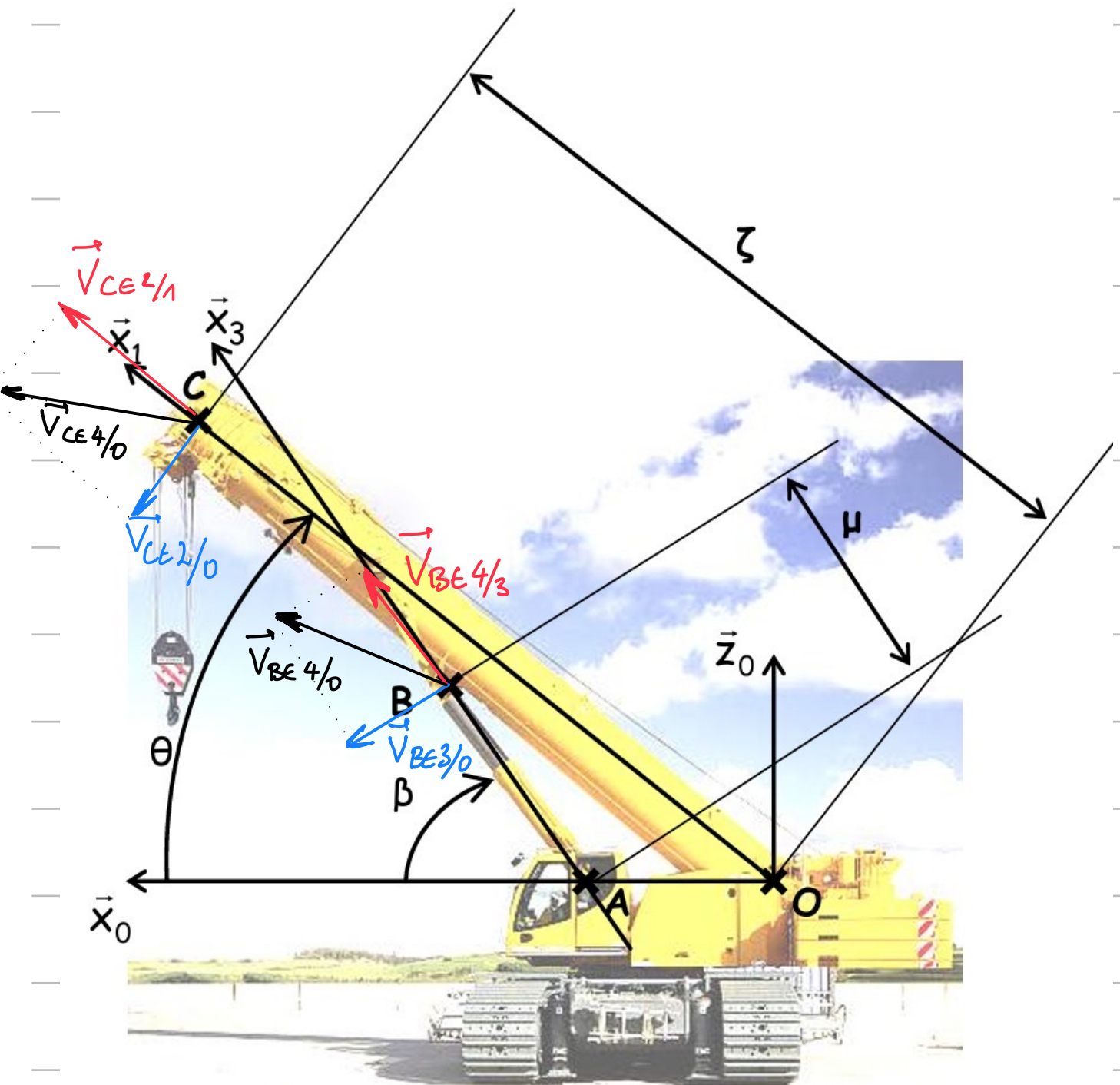
$$Q7 : \vec{V}_{be4/3} = \frac{d}{dt} \vec{AB} \Big|_3 = \frac{d}{dt} (\mu \vec{x}_3) \Big|_3 = \dot{\mu} \vec{x}_3$$

$$Q8: \vec{V}_{BE3/0} = \vec{V}_{AE3/0} + \vec{BA} \wedge \vec{\Omega}_{3/0} = -\mu \vec{x}_3 \wedge \beta \vec{y}_3 = \underline{-\mu\beta \vec{z}_3}$$

$$Q9: \vec{V}_{BE4/0} = \vec{V}_{BE4/3} + \vec{V}_{BE3/0} = \mu \dot{x}_3 - \mu\beta \dot{z}_3$$

$$Q10: \vec{V}_{BE4/1} = \underline{\vec{0}}$$

Q11.



FIN