

PARTIE C : Etude d'un wattmètre électronique1- Puissance active

1-1) on passe en notation complexe : $\underline{v} = V_n e^{j\omega t}$
 $\underline{i} = I_n e^{j(\omega t - \varphi)}$

on a $\underline{v} = \underline{Z} \underline{i} = (R + jX) \underline{i}$

$\Rightarrow V_n e^{j\omega t} = (R + jX) I_n e^{j\omega t} e^{-j\varphi}$

$\Rightarrow I_n e^{-j\varphi} = \frac{V_n}{R + jX}$

* $I_n = \frac{V_n}{\sqrt{R^2 + X^2}}$

* $-\varphi = \arg\left(\frac{V_n}{R + jX}\right) = -\arg(R + jX)$

$\Rightarrow \varphi = \arg(R + jX)$

$\Rightarrow \cos \varphi = \frac{R}{\sqrt{R^2 + X^2}} \quad \text{et} \quad \sin \varphi = \frac{X}{\sqrt{R^2 + X^2}}$

$\Rightarrow \tan \varphi = \frac{X}{R} \quad \Rightarrow \quad \varphi = \arctan \frac{X}{R}$

* dipôle inductif : $X = L\omega > 0$

$\Rightarrow \cos \varphi > 0 \quad \text{et} \quad \sin \varphi > 0 \quad \Rightarrow \quad \varphi > 0$

1-2) $P = \langle v(t) i(t) \rangle = \frac{1}{2} \operatorname{Re}(\underline{v} \underline{i}^*)$
 $= \frac{1}{2} \operatorname{Re}\left(V_n e^{j\omega t} I_n e^{-j(\omega t - \varphi)}\right)$
 $= \frac{1}{2} \operatorname{Re}\left(V_n I_n e^{j\varphi}\right) = \frac{V_n I_n \cos \varphi}{2}$

$P = \frac{V_n I_n \cos \varphi}{2}$

$v(t) i(t) = V_m \cos \omega t I_m \cos(\omega t - \varphi)$
 $= \frac{V_m I_m}{2} [\cos(\omega t + \varphi) + \cos \varphi]$
 $\langle v i \rangle = \frac{I_m V_m}{2} \cos \varphi$

1-3) $I_n = \frac{V_n}{\sqrt{R^2 + X^2}} = \frac{320}{\sqrt{5^2 + 10^2}}$

$I_n = 29 \text{ A}$

$\varphi = \arctan \frac{X}{R} = \arctan \frac{10}{5} = \arctan 2 = 1,1 \text{ rad} = 63^\circ$

$P = \frac{V_n I_n \cos \varphi}{2}$

$\Rightarrow P = 2,0 \text{ kW}$

2- Principe du wattmètre électronique

2-1) $\langle v_2 \rangle = -\langle v_1 \rangle = -K \langle v_2 v_2 \rangle$

$= -K h_a h_b \langle v(t) i(t) \rangle = -K h_a h_b P$

$\Rightarrow h_w = -K h_a h_b$

2-2) $P = \frac{\langle v_2 \rangle}{h_w} = \frac{\langle v_2 \rangle}{-K h_a h_b} \Rightarrow P = 3,75 \text{ kW}$

3- Etude du montage (filtre passe-bas)

3-1) en A: $V_A = \frac{\frac{V_1}{R} + \frac{V_2}{R} + \frac{V_B}{R} + jC_2 \omega \cdot 0}{\frac{1}{R} + \frac{1}{R} + \frac{1}{R} + jC_2 \omega}$

$\Rightarrow V_A = \frac{V_1 + V_2 + V_B}{3 + jRC_2 \omega} \quad (1)$

en B: (AO idéal $\Rightarrow i_+ = i_- = 0$)

$\Rightarrow V_B = \frac{\frac{V_A}{R} + jC_1 \omega V_2}{\frac{1}{R} + jC_1 \omega}$

$\Rightarrow V_B = \frac{V_A + jRC_1 \omega V_2}{1 + jRC_1 \omega} \quad (2)$

3-2) on a une boucle de rétroaction entre l'entrée inverseuse et la sortie de l'AO $\Rightarrow$ régime linéaire $\Rightarrow V_+ = V_-$

on $V_+ = 0$ et $V_- = V_B \Rightarrow V_B = 0$

(1) $\Rightarrow V_A = \frac{V_1 + V_2}{3 + jRC_2 \omega}$

(2) $\Rightarrow V_A = -jRC_1 \omega V_2$

$\Rightarrow V_1 + V_2 = -jRC_1 \omega (3 + jRC_2 \omega) V_2$

$V_1 = (-1 - 3jRC_1 \omega + R^2 C_1 C_2 \omega^2) V_2$

$I = \frac{V_2}{V_1} = \frac{-1}{1 + 3jRC_1 \omega - R^2 C_1 C_2 \omega^2}$

3-3) $I = \frac{T_0}{1 + \frac{1}{Q} \frac{j\omega}{\omega_0} + \left(\frac{j\omega}{\omega_0}\right)^2}$

on identifie

Load
needs
en A.

$$T_0 = -1$$

$$\omega_0^2 = \frac{1}{R^2 C_1 C_2}$$

$$\frac{1}{Q \omega_0} = 3RC_1$$

$$\Rightarrow \omega_0 = \frac{1}{R \sqrt{C_1 C_2}}$$

$$3RC_1 \omega_0 = \frac{1}{Q}$$

$$\Rightarrow \frac{1}{Q} = 3 \sqrt{\frac{C_1}{C_2}}$$

$$3.4) \frac{1}{Q \omega_0} = 3RC_1 \Rightarrow C_1 = \frac{1}{Q 3R \omega_0} = \frac{1}{3R 2\pi f_0 Q}$$

$$\Rightarrow C_1 = 3,2 \cdot 10^{-8} \text{ F} = 32 \text{ nF}$$

$$C_2 = \frac{1}{R^2 C_1 \omega_0^2} = \frac{1}{4\pi^2 f_0^2 R^2 C_1} = 1,4 \cdot 10^{-7} \text{ F}$$

$$C_2 = 140 \text{ nF}$$

$$3.5) * \omega \rightarrow 0, T \rightarrow T_0 = -1$$

$$|I| \rightarrow 1 \quad G \rightarrow 0$$

$$\varphi \rightarrow \pm \pi ?$$

$$* \omega \rightarrow \infty, T \rightarrow \frac{-1}{-\frac{\omega^2}{\omega_0^2}} = \frac{\omega_0^2}{\omega^2}$$

$$\varphi \rightarrow 0$$

$$G \rightarrow 40 \log \omega_0 - 40 \log \omega$$

pente à -20 dB/décade

$$* \omega = \omega_0, T = \frac{-1}{1 + \frac{j}{Q} - 1} = \frac{-Q}{j} = \frac{j}{Q}$$

$$\varphi = \frac{\pi}{2} \quad (\Rightarrow \text{pour } \omega \rightarrow 0, \varphi \rightarrow \pi)$$

$$|I| = \frac{1}{Q} \Rightarrow G = -20 \log \left(\frac{1}{Q} \right) = -20 \log \sqrt{2} = -3 \text{ dB}$$

$$* \text{intersection des asymptotes: } 0 = 40 \log \omega_0 - 40 \log \omega$$

$$\Rightarrow \text{pour } \omega = \omega_0 \quad (f = f_0 = 5 \text{ Hz})$$

$$3.6) T = \frac{V_2}{V_1} = \frac{-1}{1 + \frac{1}{\omega_0} j\omega + \frac{1}{\omega_0^2} (j\omega)^2}$$

$$V_2 \left(1 + \frac{1}{\omega_0} j\omega + \frac{1}{\omega_0^2} (j\omega)^2 \right) = -V_1$$

$$\text{ou } x j\omega \Leftrightarrow \frac{d}{dt}$$

$$\Rightarrow \frac{1}{\omega_0^2} \frac{d^2 V_2}{dt^2} + \frac{1}{\omega_0 Q} \frac{dV_2}{dt} + V_2 = -V_1$$

$$\Rightarrow \frac{d^2 V_2}{dt^2} + \frac{\omega}{Q} \frac{dV_2}{dt} + \omega_0^2 V_2 = -\omega_0^2 V_1$$

$$3.7) v_1 = K_{A_2} v_2 = K_{A_2} h_2 v(t) i(t)$$

$$v_1 = K_{A_2} h_2 V_n I_n \cos(\omega t) \cos(\omega t - \varphi)$$

$$= K_{A_2} h_2 V_n I_n \cos \omega t (\cos \omega t \cos \varphi + \sin \omega t \sin \varphi)$$

$$= K_{A_2} h_2 V_n I_n (\cos^2 \omega t \cos \varphi + \sin \omega t \cos \omega t \sin \varphi)$$

$$= K_{A_2} h_2 V_n I_n \left(\frac{1 + \cos 2\omega t}{2} \cos \varphi + \frac{1}{2} \sin 2\omega t \sin \varphi \right)$$

$$= \frac{K_{A_2} h_2 V_n I_n}{2} (\cos \varphi + \underbrace{\cos 2\omega t \cos \varphi + \sin 2\omega t \sin \varphi}_{\cos(2\omega t - \varphi)})$$

$$v_1 = \frac{K_{A_2} h_2 V_n I_n}{2} (\cos \varphi + \cos(2\omega t - \varphi))$$

$\Rightarrow v_1$ est donc la somme de 2 termes :

$$* \frac{K_{A_2} h_2 V_n I_n}{2} \cos \varphi : \text{tension continue} = \langle v_1 \rangle$$

$$* \frac{K_{A_2} h_2 V_n I_n}{2} \cos(2\omega t - \varphi) : \text{composante alternative de pulsation } 2\omega.$$

Chacune de ces tensions va donner une tension en sortie.

$$* \text{tension continue: } \omega = 0 \Rightarrow T = -1$$

$$\Rightarrow v_2 = -\langle v_1 \rangle$$

$$* \text{composante alternative: pulsation } 2\omega = 200\pi \text{ rad.s}^{-1}$$

$$\Rightarrow \frac{\omega}{\omega_0} = \frac{200\pi}{40\pi} = 20$$

$$\Rightarrow |I| = \frac{1}{\sqrt{(1-20)^2 + 40^2 \times 20^2}} = 2,3 \cdot 10^{-2}$$

$$A_n = |I| \times \frac{K_{A_2} h_2 V_n I_n}{2} = 3,2 \cdot 10^{-2} \text{ V} = A_n$$

$$\frac{A_n}{\langle v_1 \rangle} = \frac{|I|(\omega = 200\pi)}{\cos \varphi} = \frac{2,3 \cdot 10^{-2}}{\cos 1} = 5,4 \cdot 10^{-2} = 5,4\%$$

précision relative de la mesure de P